

MICRO SWITCH EJF SERIES



FEATURES

- 1-piece spring mechanism design offering durable acute operation and nice touch feeling
- Heavy/Light operation force specifications
- High flux-tight structure
- High solder reliability
- RoHS Compliant



APPLICATIONS

- Communication equipment
- Security systems

- Office automation appliances
- General industrial machines

SPECIFICATIONS

1. ELECTRICAL

| TYPE DESCRIPTION | | EJF-0.05A | EJF-1A | EJF-3A |
|-----------------------|-------------------|------------------------|------------|------------|
| Contact Rating: | AC 125V | | 1A | 3A |
| | DC 30V | 0.05A | 0.5A | 2A |
| Contact | O.F.1.47N (150gf) | 100mΩ Max. | 100mΩ Max. | 100mΩ Max. |
| Resistance: (Initial) | O.F.0.74N (75gf) | 100mΩ Max. 100mΩ Max | | |
| Insulation Resistance | | 100 MΩ Min. at 500 VDC | | |

2. CHARACTERISTICS

| TYPE DESCRIPTION | | EJF-0.05A | EJF-1A | EJF-3A |
|-------------------------------------|---|---|------------------------------------|------------------------------------|
| Mechanical Life (Cycles Operations) | | 1,000,000 (60 operations / min) | 1,000,000 (60 operations / min) | 1,000,000 (60 operations / min) |
| Electrical Life (| (Cycles Operations) | 30,000 (15 operations / min) | 30,000 (15 operations / min) | 30,000 (15 operations / min) |
| Ambient Temp | erature | -25°C to +85°C (60%RH Max.with no icing) | | |
| Ambient Humi | dity | +5°C to +35°C (85%RH Max.) | | |
| Max. Mechanical 200 cycle/min. | | | | |
| operating cycle rate | Electrical | 30 cycle/min. | | |
| Allowable Operation speed | | 1mm to 500mm/sec (without lever) | | |
| | Between non- continuous terminal | 600 VAC for 1 min | | n |
| Dielectric Strength | Between each terminal and other exposed metal parts | 1500 VAC for 1 min | | in |
| | Between each terminal and ground | 1500 VAC for 1 min | | in |
| Vibration Resistance | Malfunction | 10 to 55 Hz at single amplitude of 0.75mm | | |
| Unit weight | | Approx 0.5g (pin plunger models) | | |

3.CORRECT USE

3-1. Terminal Connections:

Solder Terminals:

- 3-1-1. When soldering a lead wire to the terminal, first insert the lead wire conductor into the terminal hole and then perform soldering.
 - Make sure that the capacity of the soldering iron is 30W maximum and that the temperature of the soldering iron tip is approximately 300°C. Complete the soldering within 3s.
 - Using a switch with improper soldering may result in abnormal heating, possibly resulting in burn. Applying a soldering iron for more than 3s or using one that is rated at more than 30W may deteriorate the switch characteristics.
- 3-1-2. Do not apply the load to terminals at soldering. Because electric and mechanical characteristics may deteriorate due to the load.

Quick-Connect Terminals:

- 3-1-3. When soldering the lead wire to the PCB terminal, pay careful attention so that the flux and solder liquid level does not exceed the PCB level.
- 3-1-4. Do not apply excessive force horizontally or vertically to the terminals,

otherwise the terminal may be deformed or the housing may be damaged.

3-2. Operating Condition:

- 3-2-1. Do not leave a switch with the actuator depressed for a long time, otherwise the parts of the switch may soon deteriorate and its operating characteristics may change.
- 3-2-2. Do not apply oil, grease, or other lubricants to the sliding parts of a switch. The intrusion of oil, grease, or other lubricants into the internal part may cause operating failure or contact failure.

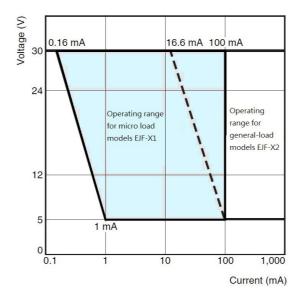
3-3. Operating Stroke Setting:

3-3-1. Take particular care in setting the operating stroke for the pin plunger models. Make sure that the operating stroke is 70% to 100% of the rated OT distance. Do not operate the actuator exceeding the OT distance, otherwise the durability of the Switch may be shortened.

3-4. Using Micro Loads:

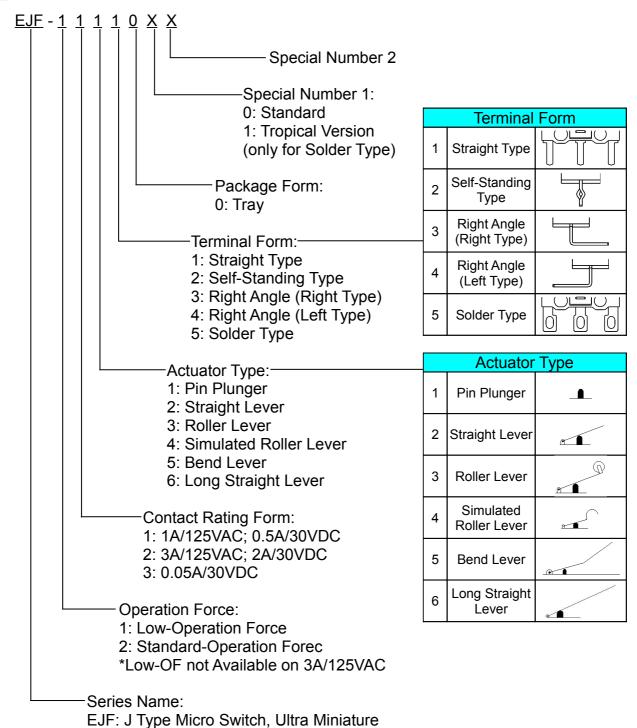
- 3-4-1. Using a model for ordinary loads to open or close the contact of a micro load circuit may result in faulty contact.
- 3-4-2. Contact faults may occur if a Switch for a general-load is used to switch a micro load circuit. Use switches in the operating range shown in the following diagram. However, even when using micro load models within the operating range shown here, if inrush current occurs when the contact is opened or closed, it may increase contact wear and so decrease durability. Therefore, insert a contact protection circuit where necessary. The minimum applicable load is the N-level reference value. This value indicates the malfunction reference level for the reliability level of 60% (λ ₆₀).

The equation, $\lambda_{60} = 0.5 \times 10^{-6}$ /operations indicates that the estimated malfunction rate is less than 1/2,000,000 operations with a reliability level of 60%.





PART NUMBERING SYSTEM

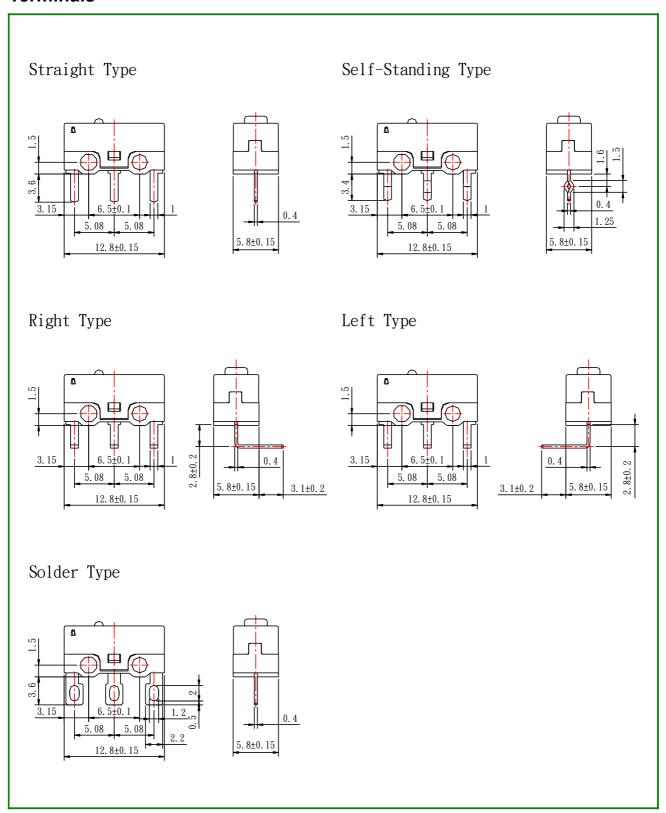


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DIMENSIONS

Terminals

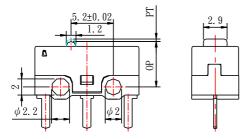




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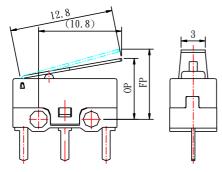
Actuator

Pin Plunger



| | Operating OF type Characteristics | Low-0F | Standard-0F |
|----|-----------------------------------|-------------------|--------------------|
| 1. | Operating Force (OF) | 75gf (0.74N) Max. | 150gf (1.47N) Max. |
| 2. | Release Force (RF) | 5gf (0.05N) Min. | 20gf (0.20N) Min. |
| 3. | Pretravel (PT) | 0.5mm Max. | |
| 4. | Movement Differential (MD) | 0.12mm Max. | |
| 5. | Operating Position (OP) | 5.5±0.3mm | |

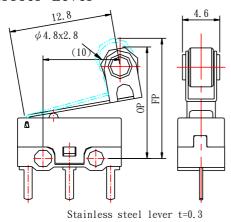
Straight Lever



Stainless steel lever t=0.3

| | Operating OF type Characteristics | Low-0F | Standard-0F |
|----|-----------------------------------|-------------------|-------------------|
| 1. | Operating Force (OF) | 40gf (0.39N) Max. | 80gf (0.78N) Max. |
| 2. | Release Force (RF) | 2gf (0.02N) Min. | 5gf (0.05N) Min. |
| 3. | Free Position (FP) | 10mm Max. | |
| 4. | Movement Differential (MD) | 0.5mm Max. | |
| 5. | Operating Position (OP) | 6.8±1.5mm | |

Roller Lever



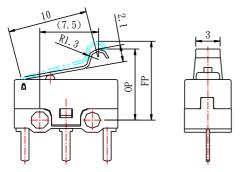
| | Operating OF type Characteristics | Low-0F | Standard-0F |
|----|-----------------------------------|-------------------|-------------------|
| 1. | Operating Force (OF) | 40gf (0.39N) Max. | 80gf (0.78N) Max. |
| 2. | Release Force (RF) | 2gf (0.02N) Min. | 5gf (0.05N) Min. |
| 3. | Free Position (FP) | 16.5mm Max. | |
| 4. | Movement Differential (MD) | 0.5mm Max. | |
| 5. | Operating Position (OP) | 13±2.0mm | |



■ DIMENSIONS

Actuator

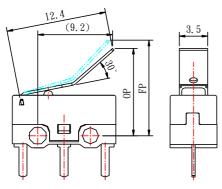
Simulated Roller Lever



Stainless steel lever t=0.3

| | Operating OF type Characteristics | Low-OF | Standard-0F |
|----|--------------------------------------|-------------------|-------------------|
| 1. | Operating Force (OF) | 40gf (0.39N) Max. | 80gf (0.78N) Max. |
| 2. | Release Force (RF) | 2gf (0.02N) Min. | 5gf (0.05N) Min. |
| 3. | Free Position (FP) | 13mm Max. | |
| 4. | Movement Differential (MD) | 0.45mm Max. | |
| 5. | Operating Position (OP) | 8.5±1.2mm | |

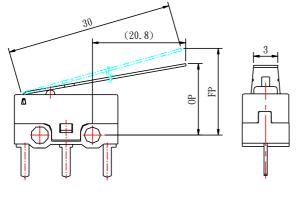
Bend Lever



| Stainl | 999 | cteel | lever | +=0 | 3 |
|--------|-----|-------|-------|-----|---|

| | Operating OF type Characteristics | Low-OF | Standard-OF |
|----|-----------------------------------|-------------------|-------------------|
| 1. | Operating Force (OF) | 40gf (0.39N) Max. | 80gf (0.78N) Max. |
| 2. | Release Force (RF) | 2gf (0.02N) Min. | 5gf (0.05N) Min. |
| 3. | Free Position (FP) | 14mm Max. | |
| 4. | Movement Differential (MD) | 0.5mm Max. | |
| 5. | Operating Position (OP) | 9.5±1.5mm | |

Long Straight Lever



| | Operating OF type Characteristics | Low-OF | Standard-0F |
|----|-----------------------------------|-------------------|-------------------|
| 1. | Operating Force (OF) | 15gf (0.39N) Max. | 22gf (0.78N) Max. |
| 2. | Release Force (RF) | 2gf (0.02N) Min. | 3gf (0.03N) Min. |
| 3. | Free Position (FP) | 15.4mm Max. | |
| 4. | Movement Differential (MD) | 3.0mm Max. | |
| 5. | Operating Position (OP) | 7. 4±2. 1mm | |

Stainless steel lever t=0.3



DIMENSIONS

Mounting

